In the Claims:

Please amend the claims as follows:

1. (currently amended) ~~Industrial~~ An industrial robot having a first part ~~(7)~~ and a second part ~~(5)~~ that are arranged to be movable with respect to each other where at least one cable ~~(11)~~ extends from the first part ~~(7)~~ to the second part ~~(5)~~ via an internal cavity ~~(12)~~, ~~characterized in that~~ wherein an excess of cable extends freely through the internal cavity ~~(12)~~ from the first part ~~(7)~~ to the second part ~~(5)~~ and ~~that~~ wherein said at least one cable is connected to at least one of the parts via a releasable contact point ~~(10)~~ that is located inside the internal cavity ~~(12)~~.

2. (currently amended) ~~Industrial~~ The robot according to claim 1, wherein ~~any preceding claims, characterized in that~~ one of said parts rotates or pivots about the other part.

3. (currently amended) ~~Industrial~~ The robot according to claim 1, wherein ~~any preceding claims, characterized in that~~ one of the parts comprises an electric motor ~~(8)~~.

4. (currently amended) ~~Industrial~~ The robot according to claim 1, wherein ~~any preceding claims, characterized in that~~ said excess of cable ~~(11)~~ forms an arch inside the internal cavity ~~(12)~~.

5. (currently amended) ~~Industrial~~ The robot according to claim 1, wherein ~~any of claims 1-6, characterized in that~~ said excess of cable ~~(11)~~ forms a spiral inside the internal cavity ~~(12)~~.

6. (currently amended) ~~Industrial~~ The robot according to claim 1, wherein ~~any of claims 1-6, characterized in that~~ said excess of cable ~~(11)~~ forms an S-shape inside the internal cavity ~~(12)~~.

7. (currently amended) ~~Industrial~~ The robot according to claim 6, wherein ~~9,~~ ~~characterized in that~~ the excess of cable ~~(11)~~ extends along an inner wall of the internal cavity ~~(12)~~.

8. (currently amended) ~~Method~~ A method of connecting at least part of at least one cable ~~(11)~~ between a first ~~(7)~~ part and a second part ~~(5)~~ of an industrial robot which are arranged to be movable with respect to each other where said at least one cable ~~(11)~~ extends from a first contact/securing point ~~(10)~~ on the first part ~~(7)~~ to a second contact/securing point on the second part ~~(5)~~ via an internal cavity ~~(12)~~, ~~characterized in~~ comprising connecting/securing said at least one cable to the first contact/securing point ~~(10)~~, moving the first and second contact/securing points into a position where they are furthest from each other, extending a length of cable ~~(11)~~ freely through the internal cavity ~~(12)~~ from the first contact/securing point ~~(10)~~ to the second contact/securing point ~~(13)~~ and connecting/securing said at least one cable releasably to the second part ~~(5)~~.